Yingling Notes

* He uses a linear model developed by poking the model/hardware and determining the sensitivities. Was there any analysis to verify the validity of this linear model over the range of operation? Do the nonlinearities obviate the linear model for a practical range of operation deflection?
* Quasi-static = rates are assumed to be zero,
* Only the PDM components change the optical prescription of an element
* How do you justify using the pseudoinverse to generate the control vector?